

Ruggedized Multi-Band, Multi-Constellation Centimeter-Accurate GNSS

Swift Navigation, in partnership with Carnegie Robotics, introduces Duro—an enclosed version of the Piksi® Multi dual-frequency RTK receiver. Built for the outdoors, Duro combines centimeter-accurate positioning with military ruggedness at a breakthrough price.

Built to Be Tough

Duro leverages design principles typically used in military hardware and results in an easy-to-deploy sensor, protected against weather, moisture, vibration, dust, water immersion and unexpected circumstances that can occur in long-term, outdoor employments.

Easy Integration

Duro's M12 connectors are sealed and industry standard, which balances ruggedization perfectly with user-friendliness. No external sealing is required to deploy in even the harshest conditions. The exposed interfaces support varied use cases without integration headaches.

Centimeter-Level Accuracy

Autonomous devices require precise navigation—especially those that perform critical functions. Swift Navigation's Piksi Multi module within Duro utilizes real-time kinematics (RTK) technology, providing location solutions that are 100 times more accurate than traditional GPS.

Fast Convergence Times

Multiple signal bands enable fast convergence times to high-precision mode. Single band RTK systems converge in minutes, while Piksi Multi converges to a high-precision solution within seconds. This allows for much faster system start times, as well as faster reacquisition, critical to robotic systems.

Field Upgradeable

Swift Navigation and Carnegie Robotics have partnered to create a product that offers a technology development platform that can easily be software-upgraded to leverage Swift Navigation's and Carnegie Robotics' future intellectual property and technology.

Leverages Piksi Multi

Multiple signal bands enable fast convergence times and multiple satellite constellations enhance availability.Piksi Multi supports GPS L1/L2 for RTK measurements and positioning and GLONASS L1/L2 measurements for PPK use cases. Other constellations such as BeiDou, Galileo, SBAS are planned to be rolled out in the near future. No additional upgrade charges for constellation upgrades.



Benefits

- Ruggedized Sensor for Long-Term Deployment
- Uses Swift Navigation's Piksi Multi
- Highly-Competitive Pricing
- Flexible Mounting Interfaces
- Future-Proof Hardware with In-Field Software Upgrades
- Intuitive LEDs for Status and Diagnostics
- Electrical Protection on all IO
- Durable and Chemical Resistant Powder-Coating
- Passive Thermal Design

Features

- IP67 rated
- Centimeter-Level Positioning
- Dual Frequency GNSS RTK
- Raw Data Outputs from On-Board MEMS IMU

Duro™

Physical & Environmental

Dimensions	130 mm x 130 mm x 65 mm
Weight	0.8 kg (Cast Al Housing)
Temperature Operating Storage	-40° C to +75° C -40° C to +85° C
Humidity	95% non-condensing
Sealing	IP67
Vibration Operating and Survival	(Random Vibe) 7.7 g
Operating and Survival	(Sinusoidal Vibe) 5 g
Mechanical Shock	(0
Operating	40 g
Survival	75 g

Electrical & I/O

Resistor

Power	
Input Voltage ¹	10 - 35 V DC
Typical Power Consumption ²	4.2 W
Antenna LNA Power Specifications	
Output Voltage	4.85 V DC
Max Output Current	100 mA
External Connector Ports	
 2 x RS232 Serial Ports with Opt Hardware Flow Control 	ional
- Ethernet support up to 100Mbp	5
- PPS, PV, 3 x Event Inputs	
- CANBus with Selectable Termir	nation

Configurable Digital Inputs and Outputs
12 V at 1A and 5 V at 250mA Power Outputs

GNSS Characteristics

GNSS Signal Tracking GPS GLONASS L1/L2³

GNSS Data Rates⁴

Measurements (Raw Data)	Up to 20 Hz
Standard Position Outputs	Up to 20 Hz
RTK Position Outputs	Up to 10 Hz
Swift Binary Protocol (SBP) and NM	1EA-0183

Maximum Operating Limits⁵

Altitude	18,000 m
Velocity	515 m/s

Position Performance Specifications

Position, Velocity & Time Accuracy

Horizontal Position Accuracy (CEP 50 in SPP Mode)	2.5 m		SERIAL M12/A/F 8 POS				
Velocity Accuracy	0.03 m/s RMS	1	Serial 0 TX				
Time Accuracy	60 ns RMS	2	Serial 0 RX			М	AUX 12-A/F 17 POS
Real Time Kinematic (RTK Accuracy 1 0)		3	CTS			1	CAN Low
- Horizontal	0.010 m + 1 ppm	4	RESERVED			2	5V Out
- Vertical	0.015 m + 1 ppm	5	GND			3	RTS
RTK Initialization Parameters		6	12 V Out	GN	SS ANTENNA TNC	4	CTS
- Initialization Time	< 10 s	7	PPS Out			5	12V Out
- Initialization Reliability	> 99%	8	RTS	Pin	Antenna	6	GND
- Solution Latency	< 30 ms			Body	Chassis	7	RESERVED
					/	8	RESERVED
			 (a) (b) (200). 			9	RESERVED
ETHERNET M12-D/F 4 POS						10	TX
1 TX +						11	Rx
2 RX +						12	CAN High
3 TX -					20 10	13	PPS
4 RX -						14	GND
						15	RESERVED
POWER	0						
POWER M12/A/M 5 POS	0					16	RESERVED
1 Voltage In	6	1				17	D0/PV
2 Chassis GND							
3 Power GND				a de la de l		R	ESERVED FOR FUTURE USE
4 PPS			Ø				
5 Event A					- 15		

¹ Maximum allowed input Voltage range. Recommended Voltage input range from 12 - 24V

 $^{\rm 2}$ $\,$ Typical power consumption by module in L1/L2 RTK positioning mode - measured at 12 V.

^a Hardware-ready for BeiDou B1/B2, Galileo E1/E5b, QZSS L1/L2 and SBAS (Satellite Based Augmentation Systems such as WAAS & EGNOS). Piksi Multi GNSS Module has the RF front end to receive these signals but there are no precise implementation dates for future satellite systems.

- ⁴ Please refer the Piksi Multi product summary for additional specifics.
- ⁵ As required by the U.S. Department of Commerce to comply with export licensing restrictions.

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